

Active Learning for Fish Detection

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① Motivations

② Litterature

③ Results

1 Motivations

2 Litterature

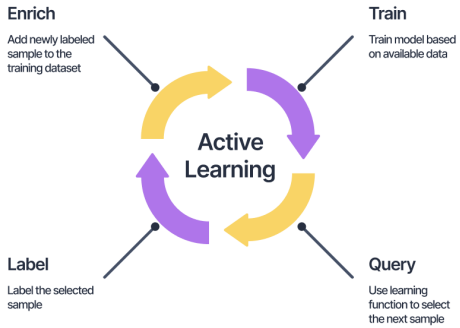
3 Results

What is Active Learning ?

Active learning is the subset of machine learning in which a learning algorithm can query a user interactively to label data with the desired outputs. The algorithm proactively selects the subset of examples to be labeled next from the pool of unlabeled data.

Goal

- Reach higher accuracy with less data
- Less time consuming labeling of data



Limitations/Challenges

- Human labeling error
- Selection bias
- Computational cost
- Complexity of the model (query by committe)
- Limited diversity

Methods

- Uncertainty** Select the examples for which the model is the least sure of its prediction.
- Diversity** Select the examples that best represent the diversity of the data set.
- Density** Select the examples which are close to the decision frontier of the model.

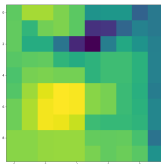
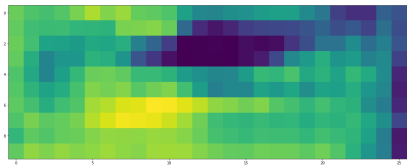
Embedding

To describe each images I chose the output features of the head's convolution layer of size $128 \times ? \times ?$

One problem : We can't compare boxes of different sizes

ROI pooling

Resize each box's feature with ROI pooling, to get 10×10 images.



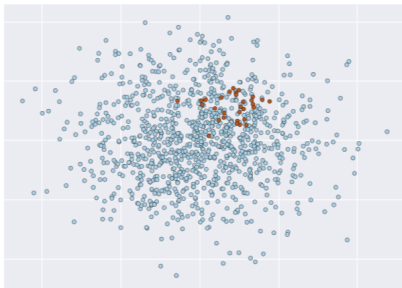
So for each images we get a $n \times 128 \times 10 \times 10$ with n the number of detections

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Representativity problem



Big difficulties for a model to learn under-represented classes.

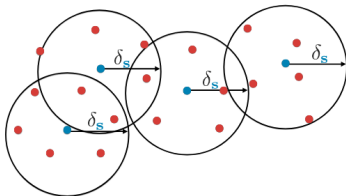
Core-Set

With Core-set we want to select representative and diverse subset of data the classification task

Advantages : avoids biases in the data set and allows a better generalization of the model

Core-Set

- Step 1 Train with random ideal data,
- Step 2 Select highest-scoring unlabeled samples (lots of variability depending on the metric),
- Step 3 Compute the distances between each point of the labeled and unlabeled data,
- Step 4 Find the k-centers such that we have the least amount of unlabeled point coverings our data pool

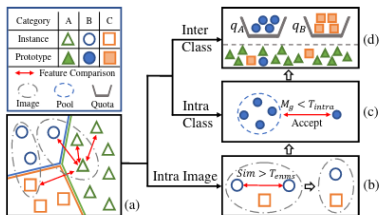


DivProto

Entropy-based Active Learning for Object Detection with Progressive Diversity Constraint

Constraints

- Intra-Image Diversity
- Intra-class Diversity
- Inter-class Diversity



Intra-Image Diversity with ENMS

Entropy-based Non Maximum suppression

Algo

- 1 Compute similarity between each box embedding
- 2 Remove one box if similarity smaller than T_{enms}
- 3 Compute image entropy from remaining detections:

$$\mathbb{H}(I_i|D_S) = \sum_{k \in [t]} -p_{i,k} \log(p_{i,k}) - (1 - p_{i,k}) \log(1 - p_{i,k})$$

Diverse Prototype for Inter-Image Diversity

For each class in image we compute his prototype:

$$proto_{i,c} = \frac{\sum_{k \in [t]} 1(c, c_{i,k}) \cdot \mathbb{H}(I_i, k) \cdot f_{i,k}}{\sum_{k \in [t]} 1(c, c_{i,k}) \cdot \mathbb{H}(I_i, k)}$$

Than compute the intra-class diversity between images having the same classes:

$$M_g(I_i, [C]) = \min_{c \in [C]} \max_{j \in |\Delta S|} Sim(proto_{j,c}, proto_{i,c})$$

Inter-Image Redundancy Rejection

Intra-class rejection tends to favor majority classes, leading to class imbalance.

Inter-class balancing

We make a selection of the C_{minor} classes that have the least occurrences

Fill a quota for each class, counter proportionnal to occurrences = labeling budget

DivProto

Algorithm 2 Diverse Prototype

Input: the labeled images \mathcal{S} the unlabeled images $\{I_i\}_{i \in [n]} - \mathcal{S}$ the budget b and the thresholds T_{intra} and T_{inter} **Output:** the selected image set $\Delta\mathcal{S}$ to be labeled**Initialize:** $\Delta\mathcal{S} := \emptyset$

- 1: Calculate the entropy $\{E_i\}$ as well as the prototypes $\{\{proto_{i,c}\}_{c \in [C]}\}$ for the set of the unlabeled images $\{I_i\}_{i \in [n]} - \mathcal{S}$ by ENMS and Eq. (3), respectively.
 - 2: Calculate the quotas $\{q_c\}_{c \in [C_{minor}]}$ based on \mathcal{S}
 - 3: Sort $\{I_i\}_{i \in [n]} - \mathcal{S}$ in descending order according to $\{E_i\}$
 - 4: **for** i in $[[\{I_i\}_{i \in [n]} - \mathcal{S}]]$ **do**
 - 5: **if** $M_g(I_i, [C]) < T_{intra}$ and $M_p(I_i, [C_{minor}]) > T_{inter}$ **then**
 - 6: Select I_i and update $\Delta\mathcal{S} := \Delta\mathcal{S} \cup \{I_i\}$
 - 7: **for** c in $[C_{minor}]$ **do**
 - 8: Update $q_c := q_c - 1$ if $p(i, c) > T_{inter}$
 - 9: Update $C_{minor} := C_{minor} - 1$ if $q_c = 0$
 - 10: **end for**
 - 11: **end if**
 - 12: **end for**
 - 13: Fill up $\Delta\mathcal{S}$ with the rest images from the sorted set $\{I_i\}_{i \in [n]} - \mathcal{S}$ until $|\Delta\mathcal{S}| = b$
-

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Results

Random weight initialization

Base

Trained on 5% of the Dataset

Entropy

Base + 20% best intra-image entropy

Random

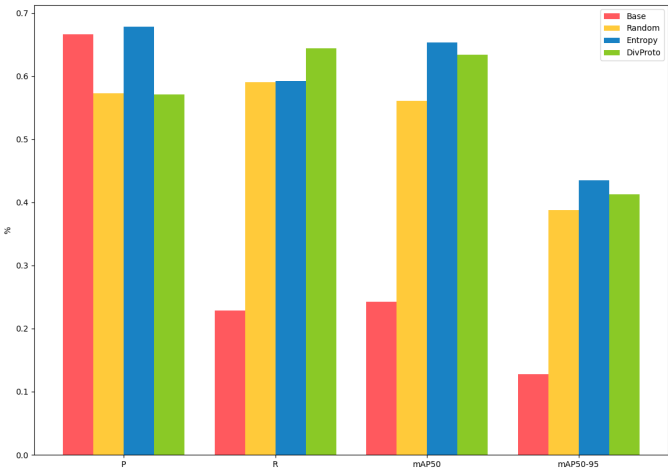
Base + random 20% of dataset

DivProto

Base + 20% best based on entropy and diversity

For each : 10% Validation - 20% Test

Results



Thanks!