Power-efficient Deep Learning Workshop Introduction

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Workshop Introduction November, 17th 2021







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2 Power efficient Deep Learning survey



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Power efficient Deep Learning 2 / 16

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## AI and Compute



#### Two Distinct Eras of Compute Usage in Training AI Systems

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"The climate impact of digital technology is bigger than aviation."

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• Al vs digital,

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- AI vs digital,
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3h of training AI is equiv. to one month of battery charges of a laptop

## Training GPT3 would cost around 200,000kWh [2]

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#### 3 Maths explicit content

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Power efficient Deep Learning 5 / 16

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#### Low bitwidth approaches

- Originally from [7] BinaryConnect
- Weights and I/O in [15, 5] XNOR-nets ++
- Quantization in [24, 20]

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## **Pruning approaches**

- Originally after training in [14] (see also [23]),
- At initalization in [9],
- During the training and using sparsity in [3, 21],

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## **Bio-inspired energy efficiency**

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## **Bio-inspired energy efficiency**



#### **Power measurements**

- [4, 10, 2] uses RAPL and nvidia-smi specific performance counters,
- [16, 10] proposes a layer by layer energy measurements comparing Mobilenets [18] to standard Inception-V3 on a ARM Cortex-A57,
- [6, 16] proposes direct power meter measurements,
- [12, 11] quantifies the carbon emission of compute here.

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## Hardwares

- CPU to GPU,
- CNNs accelerator on FPGA or ASIC, see [19, 1],
- GPU to nano-computers (Jetson Nano / Xavier).

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$min_{\theta}\ell(\theta)$	$\min_{ ho} \left\{ \mathbb{E}_{ heta \sim  ho} \ell( heta) + \mathcal{D}( ho, \pi)  ight\}$

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SGD	MCMC
differentiable, global and continuous	layerwise discrete hybrid
statistical learning	sequential learning
signal-processing based	math / stats / game theory based

- a sequence of deterministic (or i.i.d.) inputs  $z_1, \ldots, z_T \in \mathcal{Z}$ ,
- a set of weak learners  $g \in \mathcal{G}$ ,
- a loss function  $\ell(\cdot, \cdot) : \mathcal{G} \times \mathcal{Z} \to \mathbb{R}_+$ .

Goal Find a sequence of distributions such that:

$$\sum_{t=1}^{T} \mathbb{E}_{g' \sim \tilde{\rho}_t} \ell(g', z_t) - \inf_{g \in \mathcal{G}} \left\{ \sum_{t=1}^{T} \ell(g, z_t) + \lambda \mathsf{pen}(g) \right\}$$

is minimum, where pen(g) measure the 'complexity' of the decision  $g \in \mathcal{G}$ .

# Supervised framework for CNNs

- z = (x, y),  $x \in \mathcal{X}$  input space of images, time series, network,
- G := {g<sub>w</sub> : X → Y, w ∈ W}, where w are the weights of a given standard or XNOR-nets architecture. For XNOR-nets convolutions are approximated by bitwise operations:

$$x_k = \left(\mathbf{w}_k^{\mathrm{bin}} \bigoplus \mathrm{sign} \circ \mathrm{BNorm}\left(x_{k-1}\right)\right) \bigodot \mathbf{w}_k^{\mathrm{scale}},$$

• the **cross-entropy** loss function  $\ell(\hat{y}, y)$ .

#### Theorem (L. Chee and Gay, 2021)

Considering inputs  $\{(x_t, y_t), t = 1, ..., T\}$ , the decision space  $\mathcal{G}$ , and cross-entropy loss, there exists a **sequence of distributions**  $(\tilde{\rho}_t)_{t=1}^T$  on  $\mathcal{G}$  such that:

$$\sum_{t=1}^{T} \mathbb{E}_{g' \sim \tilde{\rho}_t} \ell(y_t, g'(x_t)) \leq \inf_{\mathbf{w} \in \mathcal{W}_{\mathrm{XNOR}}} \left\{ \sum_{t=1}^{T} \ell(y_t, g_{\mathbf{w}}(x_t)) + pen(g_{\mathbf{w}}) \right\} + \Delta_{\mathcal{T}},$$

where  $\Delta_T > 0$  is defined in [13] and pen(g<sub>w</sub>) measure the complexity of the network as follows:

$$pen(g_{\mathbf{w}}) = 4 \sum_{\mathbf{w} \in \{\mathbf{w}^{\text{real}}, \mathbf{w}^{\text{scale}}\}} \|\mathbf{w}\|_0 \log \left(1 + \frac{\|\mathbf{w}\|_1}{\tau \|\mathbf{w}\|_0}\right) + p_{\text{bin}} \log 2$$

- **init.**  $\lambda > 0$ , sparsity prior  $\pi$ , k = 1.
  - **1** Draw  $\hat{\mathbf{w}}_1$  from  $\pi$ .
  - **2 Repeat** for  $k = 1, \ldots, K$ :
    - Generate a proposal  $\tilde{\mathbf{w}} \sim \tilde{p}_{\hat{\mathbf{w}}_k,\sigma}$ , where  $\tilde{p}$  has mean  $\hat{\mathbf{w}}_k$ .
    - Compute:

$$\rho_j(\tilde{\mathbf{w}}, \hat{\mathbf{w}}_k) = \frac{\exp\left\{-\lambda \ell(\tilde{\mathbf{w}}, B_j)\right\} \pi(\tilde{\mathbf{w}})}{\exp\left\{-\lambda \ell(\hat{\mathbf{w}}_k, B_j)\right\} \pi(\hat{\mathbf{w}}_k)}.$$

Update

$$\hat{\mathbf{w}}_{k+1} = \begin{cases} \tilde{\mathbf{w}} & \text{with proba } 
ho_j(\tilde{\mathbf{w}}, \hat{\mathbf{w}}_k) \\ \hat{\mathbf{w}}_k & \text{otherwise.} \end{cases}$$

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## Weight distributions SGD vs MCMC



## Robustness to pruning SGD vs MCMC



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- Structural sparsity and more specific priors,
- Asynchronous and decentralized algorithms,
- Forward accelerations,
- Extensions to non-diff losses and other divergences, link with MTS problem,
- Workshop page see the dedicated page -

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